



Entropy Stable Residual Distribution Method

Scalar Equation

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The Fundamental of Entropy Control

Main Concept

Entropy Control

Numerical Results

A physical conservation law could be written in,

$$\partial_t u + \partial_x f + \partial_y g = 0 \quad (1)$$

The second law of thermodynamics will be used as an additional conservation law in the differential form,

$$\partial_t U + \partial_x F + \partial_y G \leq 0 \quad (2)$$

where,

$$U = -\rho h(s), \quad F = -\rho u h(s), \quad G = -\rho v h(s) \quad (3)$$



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There are three keywords here:

- Entropy Conservation: The entropy will not be increased or decreased.
- Entropy Stability: The entropy will always be generated with physical (correct) sign.
- Entropy Consistency: The entropy will always be generated with physical (correct) sign and amount.



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Consider a new signal distribution for RD methods,

$$\phi_i = ((f_i, g_i) - (f^*, g^*)) \cdot \vec{n}_i$$

The entropy conservation enforce that,

$$\sum_i v_i^T \phi_i = \sum_i (F_i, G_i) \cdot \vec{n}_i$$

Or,

$$\sum_i (v_i^T (f_i, g_i) \cdot \vec{n}_i) - (f^*, g^*) \sum_i (v_i^T \vec{n}_i) = \sum_i (F_i, G_i) \cdot \vec{n}_i$$



New RD Proposal

Based on Entropy Control

Entropy Control

Numerical Results

We propose an artificial terms which alters the signals distribution in the following form.

$$\begin{aligned}\phi_i = & \frac{1}{2}(f_i - f^*, g_i - g^*) \cdot \vec{n}_i \\ & - \alpha(v_j - v_i) - \beta(v_k - v_j) - \gamma(v_i - v_k)\end{aligned}\tag{4}$$

where (j, k) are the neighboring points to node i and that are to be determined.



New RD Proposal

Connection to the Entropy Stability

Entropy Control

Numerical
Results

The entropy generation will be,

$$\begin{aligned}\dot{U} &= \sum_i (F_i, G_i) \cdot \vec{n}_i - \sum_i \mathbf{v}_i^T (f_i, g_i) \cdot \vec{n}_i + (f^*, g^*) \sum_i (\mathbf{v}_i^T \vec{n}_i) \\ &\quad + \sum_i \mathbf{v}_i^T (\alpha(\mathbf{v}_j - \mathbf{v}_i) + \beta(\mathbf{v}_k - \mathbf{v}_j) + \gamma(\mathbf{v}_i - \mathbf{v}_k)) \\ &= - \sum_i \mathbf{v}_i^T (\alpha(\mathbf{v}_i - \mathbf{v}_j) + \beta(\mathbf{v}_j - \mathbf{v}_k) + \gamma(\mathbf{v}_k - \mathbf{v}_i)) \\ &= - \frac{\alpha - \gamma}{2} ((\mathbf{v}_1 - \mathbf{v}_2)^2 + (\mathbf{v}_2 - \mathbf{v}_3)^2 + (\mathbf{v}_3 - \mathbf{v}_1)^2) \\ &\quad - \beta(\mathbf{v}_1 \mathbf{v}_2 - \mathbf{v}_2 \mathbf{v}_1 + \mathbf{v}_2 \mathbf{v}_3 - \mathbf{v}_3 \mathbf{v}_2 + \mathbf{v}_3 \mathbf{v}_1 - \mathbf{v}_1 \mathbf{v}_3) \leq 0 \\ \alpha &> \gamma, \quad \forall \beta \quad \rightarrow \quad \alpha > 0, \quad \gamma = -\alpha, \quad \forall \beta\end{aligned}$$



Recovery of N-scheme

Entropy Stabel

In order to have an overview about the α and β we match the formulation to classical N approach. ($v_{ij} = v_i - v_j$)

$$\alpha = \begin{cases} \frac{(v_{ij} + v_{ik})\phi^T}{6(v_{ij}^2 + v_{jk}^2 + v_{ki}^2)} & \text{Two-Target} \\ \frac{k_j v_{ji}(v_{ij} + v_{kj}) + k_k v_{ki}(v_{ik} + v_{jk})}{6(v_{ij}^2 + v_{jk}^2 + v_{ki}^2)} & \text{One-Target} \end{cases}$$
$$\beta = \begin{cases} \frac{(v_{ji} + v_{ki})(k_i v_{jk} + k_j v_{ki} + k_k v_{ij})}{6(v_{ij}^2 + v_{jk}^2 + v_{ki}^2)} & \text{Two-Target} \\ \left(\frac{k_k - k_j}{12}\right) \left(1 - \frac{6v_{jk}^2}{v_{ij}^2 + v_{jk}^2 + v_{ki}^2}\right) & \text{One-Target} \end{cases}$$



Recovery of N-scheme

Entropy Consistent

Entropy Control

Numerical Results

For a linear case the N-scheme and LDA has this relation,

$$\phi_i^N = \phi_i^{\text{LDA}} + K_i^+(u_i - \hat{u}^+), \quad \hat{u}^+ = \frac{\sum_{\rho} k_{\rho}^+ u_{\rho}}{\sum_{\rho} k_{\rho}^+}$$

$$\phi_i^{\text{N}(m)} = \phi_i^{\text{LDA}} + K_i^+(u_i - \hat{u}^+) + K_i^{+,m}(u_i - \hat{u}^{+,m})$$
$$K_i^{+,m} = \kappa \vec{\lambda} \cdot \vec{n}_i$$

$$\phi_i^{\text{N}(m)} = \phi_i^N + K_i^{+,m}(u_i - \hat{u}^{+,m}),$$



Recovery of N-scheme

Entropy Consistent

Entropy Control

Numerical Results

The amount of entropy generation based on calculation of α for a two target cell will be,

$$\alpha^m = \kappa \left(\frac{k_j k_k v_{jk}^2}{2 (k_j + k_k) (v_{ij}^2 + v_{jk}^2 + v_{ki}^2)} \right) > 0$$

$$\alpha^N = \frac{(v_{ij} + v_{ik}) \phi^T}{6 (v_{ij}^2 + v_{jk}^2 + v_{ki}^2)}$$

$$\alpha^{N(m)} = \alpha^N + \alpha^m$$



Recovery of PSI

Minmod Limiter

Entropy Control

Numerical Results

For entropy approach of scalar equation minmod limiter could be applied. Therefore,

$$\Omega_i^{\text{LMT}} = \frac{\max(0, \Omega_i)}{\sum_p \max(0, \Omega_p)} \quad \Omega_i = \frac{\phi_i}{\phi^{\text{total}}} \quad (5)$$

This limiter could implement on the N and Lax-Friedrichs approaches.

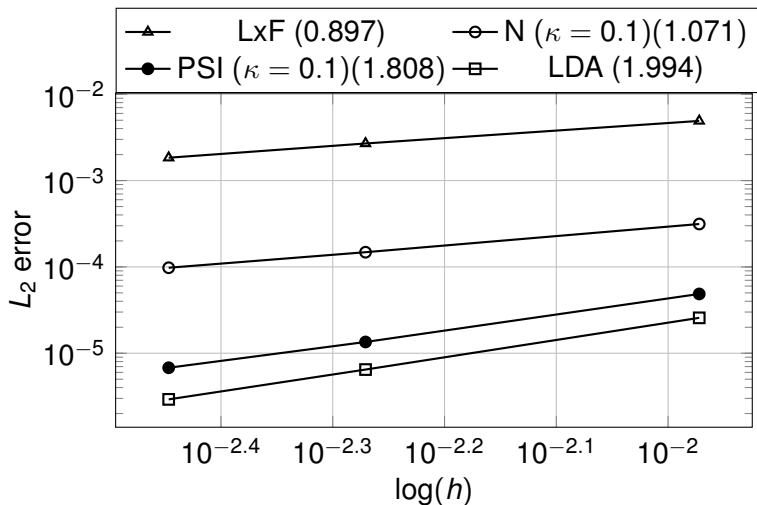


Numerical Results

Order of Accuracy

Entropy Control

Numerical
Results



Thank You



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