

Entropy Stable Residual Distribution Method Scalar Equation

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April 6, 2016

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Linear 2D Advection Signal Distribution

Scalar Results

Euler Results

Here are the scalar signal distribution,

$$\begin{cases} \phi_{i}^{iso} - \frac{1}{2}\alpha[\mathbf{V}]_{ji} - \frac{1}{2}\beta[\mathbf{V}]_{kj} - \frac{1}{2}\gamma[\mathbf{V}]_{ik} = \tilde{\phi}_{i} \\ \phi_{j}^{iso} - \frac{1}{2}\alpha[\mathbf{V}]_{kj} - \frac{1}{2}\beta[\mathbf{V}]_{ik} - \frac{1}{2}\gamma[\mathbf{V}]_{ji} = \tilde{\phi}_{j} \\ \phi_{k}^{iso} - \frac{1}{2}\alpha[\mathbf{V}]_{ik} - \frac{1}{2}\beta[\mathbf{V}]_{ji} - \frac{1}{2}\gamma[\mathbf{V}]_{kj} = \tilde{\phi}_{k} \end{cases}$$
(1)

$$\alpha \ge \mathbf{0} \qquad , \gamma = -\alpha, \qquad \forall \beta (\beta = \mathbf{0})$$
 (2)

$$\begin{cases} \phi_i^{\text{art}} = -\frac{1}{2}\alpha \left([\mathbf{V}]_{ji} - [\mathbf{V}]_{ik} \right) \\ \phi_j^{\text{art}} = -\frac{1}{2}\alpha \left([\mathbf{V}]_{kj} - [\mathbf{V}]_{ji} \right) \\ \phi_k^{\text{art}} = -\frac{1}{2}\alpha \left([\mathbf{V}]_{ik} - [\mathbf{V}]_{kj} \right) \end{cases}$$
(3)



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Linear 2D Advection Order of Accuracy

Scalar Results





Linear 2D Advection

Scalar Results





Linear 2D Burgers Order of Accuracy







Linear 2D Burgers Order of Accuracy



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Here is the Euler signal distribution,

$$\begin{split} \boldsymbol{\phi}_{i} = \quad \underbrace{\frac{1}{2} \left(\boldsymbol{\vec{f}}_{i} - \boldsymbol{\vec{f}^{\mathcal{C}}} \right) \cdot \boldsymbol{\vec{n}}_{i}}_{\boldsymbol{\phi}_{i}^{\text{iso}}} \\ - \quad \hat{\boldsymbol{R}} \hat{\boldsymbol{D}}_{\alpha} \hat{\boldsymbol{R}}^{T} [\boldsymbol{v}]_{jj} - \hat{\boldsymbol{R}} \hat{\boldsymbol{D}}_{\beta} \hat{\boldsymbol{R}}^{T} [\boldsymbol{v}]_{kj} - \hat{\boldsymbol{R}} \hat{\boldsymbol{D}}_{\gamma} \hat{\boldsymbol{R}}^{T} [\boldsymbol{v}]_{ik}}_{\boldsymbol{\phi}_{i}^{\text{art}}} \\ \hat{\boldsymbol{D}}_{\alpha} = \left(\alpha | \hat{\boldsymbol{\Lambda}} | \hat{\boldsymbol{S}} \right) h, \quad \hat{\boldsymbol{D}}_{\beta} = \left(\beta | \hat{\boldsymbol{\Lambda}} | \hat{\boldsymbol{S}} \right) h, \quad \hat{\boldsymbol{D}}_{\gamma} = \left(\gamma | \hat{\boldsymbol{\Lambda}} | \hat{\boldsymbol{S}} \right) h \end{split}$$





Scalar Results

One could just amplify all waves by 1 and choose the α as follows,

$$\alpha = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$
(4)

This combination will be adequate for entropy-stability. Nonetheless, because all the physical waves are amplified in the same way, solution might be diffusive.





From the Taylor series analysis of the isotropic signals and the artificial terms on the linear advection, the following results are obtained. We introduce,

$$m{lpha} = \left[egin{array}{cccc} \left(rac{h}{L_r}
ight)^q & 0 & 0 & 0 \ 0 & \left(rac{h}{L_r}
ight)^q & 0 & 0 \ 0 & 0 & \left(rac{h}{L_r}
ight)^q & 0 \ 0 & 0 & 0 & \left(rac{h}{L_r}
ight)^q \end{array}
ight]$$

Base on this α , all the waves are amplified based on a grid size (*h*) which is non-dimensionalized with the reference length (L_r) such as chord for the airfoil case.



(5)



To improve the robustness of the entropy-stable method without compromising the quality of the acoustics and shear waves, we propose adding more entropy generation to the entropy wave.

$$\boldsymbol{\alpha} = \begin{bmatrix} \left(\frac{h}{L_r}\right)^q & 0 & 0 & 0\\ 0 & 1 & 0 & 0\\ 0 & 0 & \left(\frac{h}{L_r}\right)^q & 0\\ 0 & 0 & 0 & \left(\frac{h}{L_r}\right)^q \end{bmatrix}$$
(6)

Preserving the entropy wave makes the solution more robust and stable.



Sensor Formulation

Scalar Results

Euler Results

Basic formulation,

$$\alpha_{1,3,4}^{\text{art,lim}} = \psi(S)\alpha_{1,3,4}^{\text{art,low}} + (1 - \psi(S))\alpha_{1,3,4}^{\text{art,high}}$$
(7)

Slope finding,

$$m_{jk}^{S} = \left| \frac{S_{j} - S_{k}}{l_{i}} \right|$$
(8)

Determine the maximum slope,

$$m_{\max}^S = \max(m_{\text{all edges}}^S)$$
 (9)



Ringleb Flow Order of Accuracy







Scalar Results











(e) q=0.7



(f) q=0.7-1.5 m=0.3 S=0







(i) q=0.7 (j) q=0.7-1.5 m=0.3 S=0











Euler Results 6 5 4 P/P_{∞} 3 Hafez Classic N -0-2 ----q0.7 *-*⊕− *q*0.7 − 1.5*m*0.3*S*0 *−*⊗− *q*0.7 − 1.5*m*0.3*S*2 -1.4-1.2 -1 -0.8-0.6-0.4-0.2 0 0.2 0.4 **H** х

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April 6, 2016 19/21





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April 6, 2016 20/21

