### Basic Residual Distribution: from comparison with FE and FV to 3D RD construction

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# FE, FV & RD for Steady Case

#### Finite Element Method





Finite Volume Method

### Residual Distribution Method



Elliptic and parabolic **PDF** 

Parabolic and hyperbolic PDE

*Laplace equation*

Parabolic and hyperbolic PDE

Elliptic PDE

 $\nabla^2 u = 0$ 

∂ *u*

∂*t*

 $+V \cdot F =$ 

∂*u*

∂ *t*

∂*u*

∂ *t*

Parabolic PDE

Hyperbolic PDE

 $\mathcal{L} = \alpha(\nabla^2 u)$  Heat transfer equation, diffusion equation

 $+\lambda \cdot \nabla u = 0$ wave equation  $\frac{1}{a^2} \frac{\partial u}{\partial t^2} = \nabla^2 u$ 

1  $c^2$  $\partial^2 u$ ∂ *t*

# Finite Element

• Step 1 : Multiply the governing equation with a weight function and integrate over the triangular element. Using weak formulation and integration by parts to reduce the order of partial differential equation.



 $u_h^T = \sum$ *j*∈*T*  $\psi^T(x, y)u_j$ 

$$
\iint_{\Gamma} \psi_i \left( \frac{\partial u_h}{\partial t} - \nabla^2 u_h \right) d\Omega = 0
$$
\n
$$
\sum_{j \in \Gamma} \left[ \frac{du_j}{dt} \iint_{\Gamma} \psi_i \psi_j d\Omega + (\nabla \psi_i \cdot \nabla \psi_j) u_j \iint_{\Gamma} d\Omega \right] = 0
$$

- Step 2 : Assembly all the elements and form *n* equations for *n* nodes in the domain.
- Step 3 : Solve the simultaneous system of equation.

### **Bonus**

 Connect all the approximate value at intersection points using Lagrange interpolation

# Finite Volume



- Step 1 : Create triangular primary elements and median dual cell.
- Step 2 : Emphasize on median dual cell. Equate the flux leaving the median dual cell is balanced out by the flux entering the median dual cell.

<u>Stopping criteria :</u> *flux leaving = flux entering*

$$
u_i^{k+1} = u_i^k - \frac{\Delta t}{S_i} \sum_{k \in k_j} (F_i^* \cdot n_{ij}^L + F_i^* \cdot n_{ij}^R)
$$

 $u_i^{k+1} = u_i^k -$ Δ*t Si* ∑ *k* ∈*k <sup>j</sup>* Second-order accurate scheme  $u_i^{k+1} = u_i^k - \frac{\Delta t}{S} \sum_i ((F_i^+ + \nabla F_i \cdot \Delta x_{ij}^L) \cdot n_{ij}^L + (F_i^+ + \nabla F_i \cdot \Delta x_{ij}^R) \cdot n_{ij}^R)$ 

First-order accurate scheme

# Residual Distribution

$$
\Phi^T = \iint_T \nabla \cdot F \, d\Omega = \oint_{\partial T} F \cdot d\Omega
$$

- Step 1 : Create triangular primary elements.
- Step 2: Calculate flux residual or flux fluctuation  $\;\;\Phi^{\scriptscriptstyle T}\;$
- Step 3 : Distribute the residual or split the fluctuation according to characteristic speed.

Driving mechanism : If the residual is not zero, just distribute it.

 $\Phi^T \rightarrow 0$ Stopping criteria :

λ

# Residual Distribution for Time-Dependent

**Steady Case** ∇⋅*F*=0



$$
\Phi^T = \iint_T \nabla \cdot F \, d\Omega = \oint_{\partial T} F \cdot dl \to 0
$$

Driving the residual within each element T towards zero.

Eventually, the fluctuation approaches zero.

Unsteady Case 
$$
\frac{\partial u}{\partial t} + \nabla \cdot F = 0
$$

$$
\Phi^T = \iint_T \nabla \cdot F \, d\Omega = \oint_{\partial T} F \cdot d\mathbf{l} \rightarrow -\left(\frac{S_T}{3}\right) \sum_{j \in T} \left(\frac{\partial u_j}{\partial t}\right)
$$

The residual at every single time step is no longer be zero, but some other values.

## Time Discretization

Therefore, in time-dependent cases, the spatial flux has to be evaluated, and then updated with proper time-marching scheme.

First-order accurate

*Forward-Euler*

$$
\left(\frac{du}{dt}\right)^n \approx \frac{u^{n+1}-u^n}{\Delta t} + O\left(\Delta t\right)
$$

$$
\frac{du}{dt} = -\frac{\Delta t}{S_i} \sum_{T \in \cup \Delta_i} \beta_i^T (\boldsymbol{\Phi}^T(\boldsymbol{u}^n))
$$

#### Second-order accurate

*Backward-time*

$$
\left(\frac{du}{dt}\right)^{n+1} \approx \frac{3u^{n+1} - 4u^{n} + u^{n-1}}{2\Delta t} + O\left(\Delta t^{2}\right)
$$

*Leapfrog-time*

$$
\left(\frac{du}{dt}\right)^n \approx \frac{u^{n+1}-u^{n-1}}{2\,\Delta\,t} + O\left(\Delta\,t^2\right)
$$

$$
\text{Predictor-corrector } \left(\frac{du}{dt}\right)^{n+\frac{1}{2}} \approx \frac{u^{n+1}-u^n}{\Delta t} + O\left(\Delta t^2\right)
$$
\n
$$
(RK2)
$$

$$
\frac{du}{dt} = -\frac{\Delta t}{S_i} \sum_{T \in \cup \Delta_i} \beta_i^T \Phi^T(u^{n+1})
$$
\n
$$
\frac{du}{dt} = -\frac{\Delta t}{S_i} \sum_{T \in \cup \Delta_i} \beta_i^T \Phi^T(u^n)
$$
\n
$$
u^{n+\frac{1}{2}} = u^n - \frac{\Delta t/2}{S_i} \sum_{T \in \cup \Delta_i} \beta_i^T \Phi^T(u^n)
$$
\n
$$
\frac{du}{dt} = -\frac{\Delta t}{S_i} \sum_{T \in \cup \Delta_i} \beta_i^T \Phi^T(u^{n+\frac{1}{2}})
$$

# Flux Residual



The flux residual is

$$
\Phi^T = \sum_{j \in T} k_j u_j = \sum_{j \in T} \left( \frac{1}{2} \lambda \cdot n_j \right) u_j
$$

The convention of inward scaled normal in RD to calculate flux residual is equivalent to evaluating the average of the flux across every single edge..

$$
j=2
$$
  

$$
\Phi^{T} = \iint_{T} \nabla \cdot F = \oint_{\partial T} F \cdot dl \approx \sum_{j\in T} \frac{(F_{j+1} + F_{j-1})}{2} \cdot l_{j} = \sum_{j\in T} k_{j} u_{j}
$$
  

$$
j=0
$$

# Distribution Coefficient & Temporal Update

 $\beta_j =$ 1 3

> Space-centered Space-centered<br>(Galerkin type) Upwind LDA

 $2 = u<sup>n</sup>$ 

 $u_i^{n+1} = u_i^n -$ 

 $\Delta t/2$ 

RK2

Δ *t*

 $\sum_i \beta_i^T S_T$ 

 $\beta_i^T\, \overline{S}_T$ 

∑  $T \in \cup \Delta_i$ 

 $T \in \cup \Delta$ 

*u*

 $n + \frac{1}{2}$ 



 $\beta_i^T \, \Phi^T \big( u^n \big)$ 

 $n + \frac{1}{2}$ 2 )

 $\beta_i^T \Phi^T(u)$ 

 $\sum$  $T \in \cup \Delta_i$ 

∑  $T \in \cup \Delta$ <sub>*i*</sub>

RK2

$$
u^{n+\frac{1}{2}} = u^n - \frac{\Delta t/2}{S_i} \sum_{T \in \cup_{\Delta_i}} \frac{1}{3} \Phi^T(u^n)
$$
  

$$
u_i^{n+1} = u_i^n - \frac{\Delta t}{S_i} \sum_{T \in \cup_{\Delta_i}} \frac{1}{3} \Phi^T(u^{n+\frac{1}{2}})
$$

# RD in Three Dimension



The flux residual is

$$
\Phi^T = \sum_{j \in T} k_j u_j = \sum_{j \in T} \left( \frac{1}{3} \lambda \mathcal{S}_j \right) u_j
$$

*sj* is the inward scaled normal, with magnitude equal to the plane area.



# Mesh Generation





### Meshing in 3D





#### Distribution Coefficient & Temporal Update Space-centered Space-centered<br>(Galerkin type) Upwind LDA  $\beta_j =$ 1 4  $\beta_j =$  $k_j^+$  $\sum_{i} k_j^*$ *j*∈*T u*  $n + \frac{1}{2}$  $2 = u<sup>n</sup>$  —  $\Delta t/2$ *Vi* ∑  $T \in \cup \Delta$ <sup>*i*</sup> 1 4  $\Phi^T(u^n)$  $u_i^{n+1} = u_i^n -$ Δ*t Vi* ∑  $T \in \cup \Delta$ <sup>*i*</sup> 1 4  $\Phi^T(u)$  $n + \frac{1}{2}$ 2 ) RK2 *u*  $n + \frac{1}{2}$  $2 = u<sup>n</sup>$  $\Delta t/2$ ∑  $T \in \cup \Delta_i$  $\beta_i^T\,V\strut_T$ ∑  $T \in \cup \Delta_i$  $\beta_i^T \, \Phi^T \big( u^n \big)$  $u_i^{n+1} = u_i^n -$ Δ *t*  $\sum_i \beta_i^T V_T$  $T \in \cup \Lambda$ ∑  $T \in \cup \Delta$ <sub>*i*</sub>  $\beta_i^T \Phi^T (u)$  $n + \frac{1}{2}$ 2 ) RK2 3-target 2-target 1-target

## Possible Test Cases?

The solution must fulfill the governing equation

$$
\frac{\partial u}{\partial t} + \lambda \cdot \nabla u = 0
$$

One example that we can think of is

$$
u(x, y, z, t) = u_0 \cos(k_x x + k_y y + k_z z - \omega t)
$$

provided that

 $\lambda_x k_x + \lambda_y k_y + \lambda_z k_z = \omega$ 

